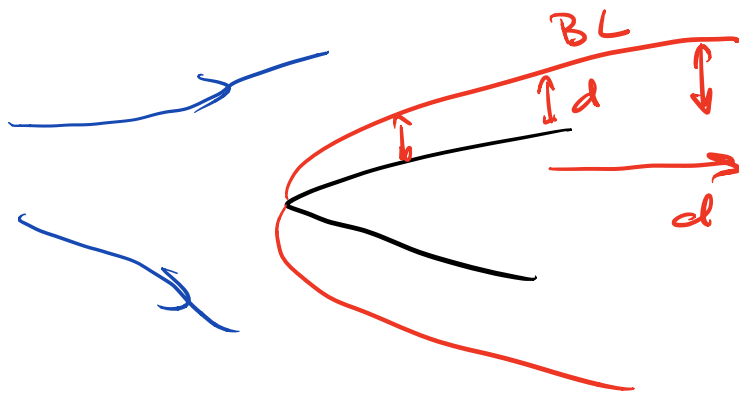
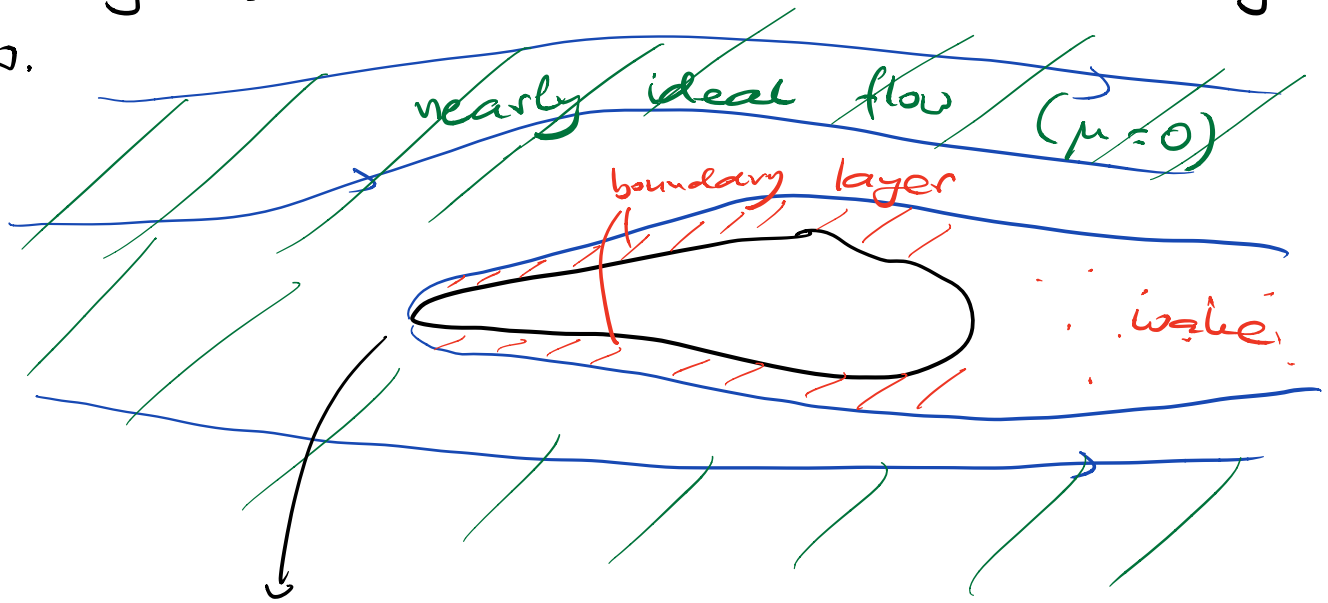


THE EKMAN LAYER

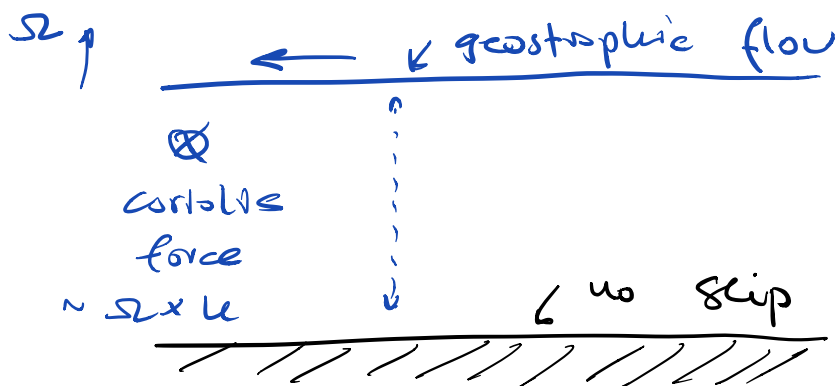
Boundary layers arise near a body in a nearly ideal flow.



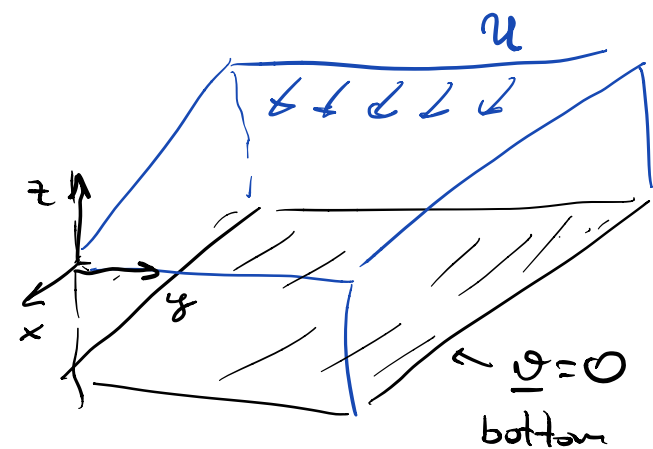
The B.L. thickens along the flow direction.

Ekman boundary layer in a rotating system

- Fluid in geostrophic flow
- $Ro = \frac{u}{2L\Omega} \ll 1$ Coriolis force important for the formation of boundary layers



Ekman layer solution



Top boundary:

geostrophic flow

$$-2 \underline{\Omega} \times \underline{v} = \frac{1}{\rho} \nabla p^*$$

with

$$v_x = u ; v_y = 0$$

$$p^* = -2 \rho \Omega u y \quad (\text{like last week})$$

Bottom boundary:

$$\underline{v} = 0 \quad (\text{no slip})$$

Symmetries:

- solution invariant in x, y
- we are looking for a solution $\underline{v} = \underline{v}(z)$

Mass conservation:

$$\frac{\partial v_z}{\partial z} = 0 \rightarrow v_z = \text{const} = 0$$

because $v_z(0) = 0$

- The transition flow is horizontal and independent of x, y but varies with z .

- N-S equations simplify because

$$(\underline{u} \cdot \nabla) \underline{u} = \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} \right) \underline{v}(z) = 0 \quad \text{vanishes}$$

we include viscosity & the Coriolis force

- steady case

N-S equations $2 \underline{\Omega} \times \underline{v} - \frac{1}{\rho} \nabla p^* + \nu \nabla^2 \underline{v} = 0$

$(\underline{\Omega} = \Omega \hat{e}_z)$
 $\nabla^2 \uparrow$

Components:

$$\begin{cases} 0 = 2\Omega v_y - \frac{1}{\rho} \frac{\partial p^*}{\partial x} + \nu \frac{\partial^2}{\partial z^2} v_x \\ 0 = -2\Omega v_x - \frac{1}{\rho} \frac{\partial p^*}{\partial y} + \nu \frac{\partial^2}{\partial z^2} v_y \\ 0 = -\frac{1}{\rho} \frac{\partial p^*}{\partial z} \end{cases}$$

$\Rightarrow p^*$ independent of z , so equal to $p^* = -2\rho\Omega u_y$
(top boundary)

The eqs. of motion:

$$\begin{cases} \nu \frac{\partial^2}{\partial z^2} v_x = -2\Omega v_y \\ \nu \frac{\partial^2}{\partial z^2} v_y = -2\Omega(u - v_x) \end{cases} \quad \begin{array}{l} \rightarrow v_y = -\frac{\nu}{2\Omega} \frac{\partial^2}{\partial z^2} v_x \\ \rightarrow \end{array}$$

$$\frac{\partial^4}{\partial z^4} (u - v_x) = -\frac{4\Omega^2}{\nu^2} (u - v_x)$$

\rightarrow solution: linear combination of 4 terms with e^{kz}

$$k^4 = -\frac{4\Omega^2}{\nu^2}$$

Define $\delta = \sqrt{\frac{\nu}{\Omega}}$ $\delta \sim \text{length}$

$$\kappa^4 = -\frac{4}{\delta^4}$$

$$\kappa = \pm \frac{1 \pm i}{\delta}$$

$\text{Re}(\kappa) > 0$ no good

only $\kappa = -\frac{1+i}{\delta}$ and $\alpha = -\frac{1-i}{\delta}$

The general solution is

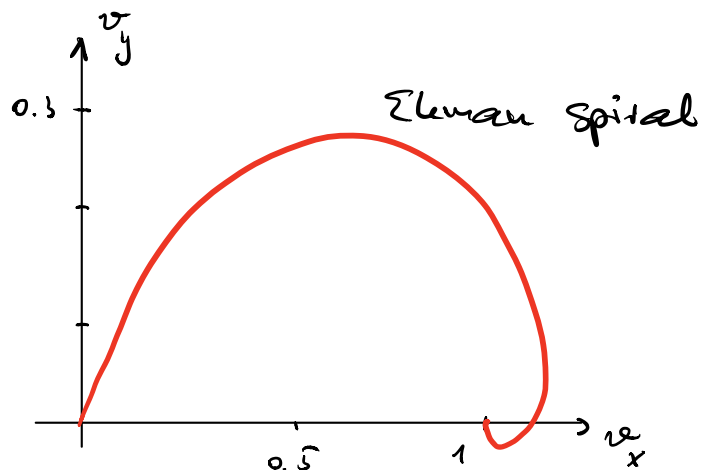
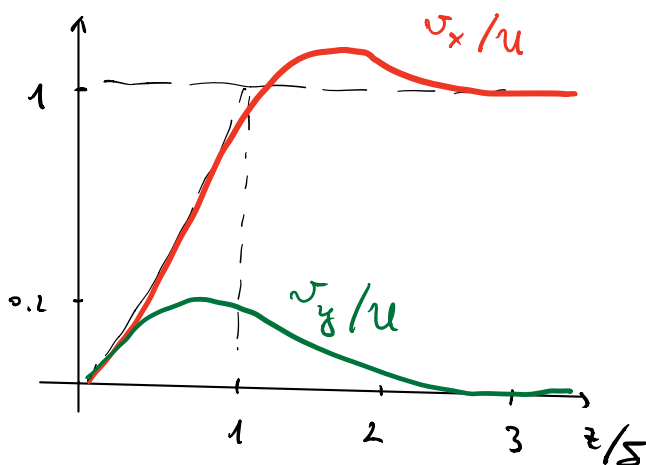
$$\begin{cases} u - v_x = A e^{-(1+i)z/\delta} + B e^{-(1-i)z/\delta} \\ v_y = i(A e^{-(1+i)z/\delta} - B e^{-(1-i)z/\delta}) \end{cases}$$

$$v_x(z=0) = v_y(z=0) = 0, \text{ so } A = B = \frac{u}{2}$$

The final solution:

$$\begin{cases} v_x = u(1 - e^{-z/\delta} \cos z/\delta) \\ v_y = u e^{-z/\delta} \sin z/\delta \end{cases}$$

- δ is a measure of the thickness of the Ekman layer.
- δ independent of u .



At middle latitudes $\delta \sim 55 \text{ cm}$ for $v = 1.5 \cdot 10^{-5} \frac{\text{m}^2}{\text{s}}$
(for the atmosphere)

Measured thickness $\sim 1 \text{ km}$

Why? Atmosphere is turbulent (not laminar)
and effective viscosity can be $\sim 10^6 \nu$

Ref: J. Pedlosky, Geophysical Fluid Dynamics, Springer
1987

Ekman upwelling & suction

If $u = (u_x, u_y, 0)$

the solution becomes:

$$(*) \begin{cases} v_x = u_x (1 - e^{-z/\delta} \cos z/\delta) - u_y e^{-z/\delta} \sin z/\delta \\ v_y = u_y (1 - e^{-z/\delta} \cos z/\delta) + u_x e^{-z/\delta} \sin z/\delta \end{cases}$$

If the velocity components $u_x(x, y)$ and $u_y(x, y)$
change slowly with x and y on a large scale $L \gg \delta$
(*) is still valid because δ is independent of u .

• Slowly varying geostrophic flow generates a non-zero
vertical flow $u_z(x, y)$.

$$\nabla \cdot \underline{v} = \partial_x v_x + \partial_y v_y + \partial_z v_z = 0 \quad \underbrace{\partial_x u_y - \partial_y u_x}_{\omega_z} \quad \text{geostrophic flow vorticity}$$

$$\Rightarrow \partial_z v_z = -(\partial_x v_x + \partial_y v_y) = (\partial_x u_y - \partial_y u_x) e^{-z/\delta} \sin z/\delta.$$

We have used the fact that $\partial_x u_x + \partial_y u_y = 0$.

Integrating over t with $v_z = 0$ for $z = 0$, we get:

$$\omega_z = \frac{1}{2} \delta (\partial_x u_y - \partial_y u_x) \left[1 - e^{-z/\delta} (\cos z/\delta + \sin z/\delta) \right]$$

Note $\omega_z \sim \frac{\delta u}{L} \ll u$ because $\frac{\delta}{L} \ll 1$

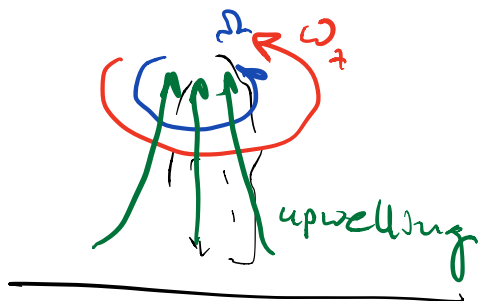
For $z \gg \delta$ there remains a vertical component

$$u_z = \frac{1}{2} \delta \omega_z$$

Note u_z is independent of z (Taylor - Proudman)

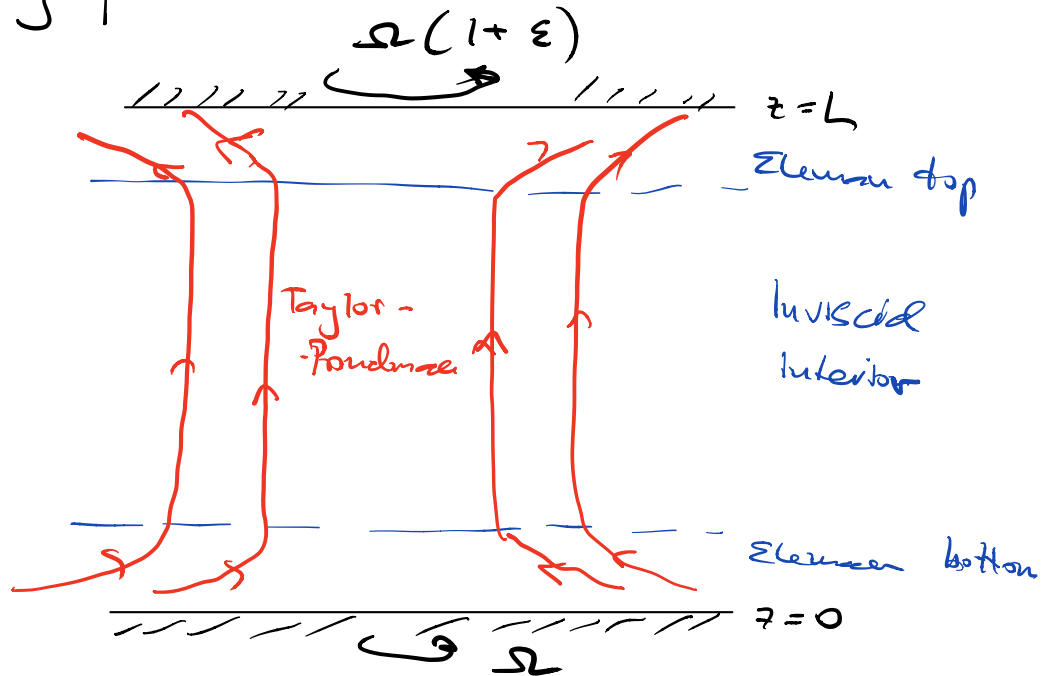
Note If $\omega_z > 0$ (of the same sign as global rotation Ω)
the fluid wells up from the Ekman layer

Ex: low p cyclone



Flow in differentially rotating boundaries

Two rotating plates



Three regions:

- 1) Boundary layers (top & bottom)
- 2) Interior flow (approx. ideal fluid)

B) Interior flow

$$(\underline{x}, y, t) \quad \underline{\Omega} = (0, 0, \Omega) \quad \underline{v} = (v_x, v_y, v_z)$$

Geostrophic flow:

$$2\Omega v_y = \frac{1}{\rho} \frac{\partial p}{\partial x}$$

$$-2\Omega v_x = \frac{1}{\rho} \frac{\partial p}{\partial y}$$

$$0 = \frac{1}{\rho} \frac{\partial p}{\partial z}$$

$$\rightarrow \frac{\partial v_z}{\partial z} = 0$$

$$\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} = 0$$

\underline{v} indep. of z .
(Taylor-Proudman)

① Bottom & top

Consider first the b.l. at $z=0$. N-S eq. takes the form:
with velocity field $\underline{u} = (u_x, u_y, u_z)$

$$-2\Omega u_y = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \frac{\partial^2 u_x}{\partial z^2}$$

$$2\Omega u_x = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \frac{\partial^2 u_y}{\partial z^2}$$

we assumed faster
variations in z
than in x, y

$$0 = -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \frac{\partial^2 u_z}{\partial z^2}$$

$$\frac{\partial u_x}{\partial x} + \frac{\partial u_y}{\partial y} + \frac{\partial u_z}{\partial z} = 0$$



u_z is much smaller than the horizontal velocity.

Repeating previous arguments, we can show

$$p = p(x, y)$$

so $\frac{\partial p}{\partial x}$ & $\frac{\partial p}{\partial y}$ same as for the interior flow,

We get:

$$-2\Omega (u_y - v_y) = \nu \frac{\partial^2 u_x}{\partial z^2}$$

$$2\Omega (u_x - v_x) = \nu \frac{\partial^2 u_y}{\partial z^2}$$

They can be integrated. → Ekman profile

Vertical flow component at the edge of the element layer:

$$u_z^E = \frac{1}{2} \delta \left(\frac{\partial v_x}{\partial y} - \frac{\partial v_y}{\partial x} \right) = \frac{1}{2} \delta \omega_I \quad \text{interior flow vorticity}$$

If now the boundary is rotating with Ω_B with respect to the rotating frame, this generalizes to

$$u_z^E = \delta \left(\frac{1}{2} \omega_I - \Omega_B \right) \quad (*)$$

If the upper boundary at $z=L$ has the angular velocity Ω_T rel. to the rotating frame, then we have

$$u_z^E(x, y) = \delta \left(\Omega_T - \frac{1}{2} \omega_I \right) \quad (*)$$

Full interior flow

T-P theorem $\frac{1}{2} \omega_I - \Omega_B = \Omega_T - \frac{1}{2} \omega_I$

That is $\omega_I = \Omega_T + \Omega_B$

In our case: $\Omega_B = 0$ $\Omega_T = \Omega \varepsilon$

we get: $\omega_I = \frac{\partial v_x}{\partial y} - \frac{\partial v_y}{\partial x} = \Omega \varepsilon$

$\frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) = \Omega \varepsilon$ in polar coordinates.

$\Rightarrow v_\theta = \frac{1}{2} \Omega \varepsilon r$

The vertical velocity:

$$w_z = \frac{1}{2} \sqrt{2\Omega} \xi$$

From incompressibility also $v_r = 0$.