

INTRO: MANY-BODY PROBLEM (IN EQUILIBRIUM)

$N \approx 10^{23}$ particles at fixed (say) (T, V)

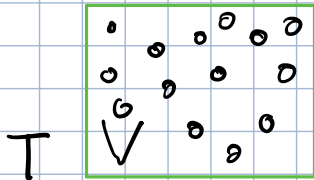
$(N \gg 1 \rightarrow N \rightarrow \infty)$

Microscopic description $\hat{H}(\{\hat{r}_i, \hat{p}_i\}_{i=1}^N)$

Macroscopic description

$p(T, V, N), \bar{z}(T, V, N, \vec{E}), \dots$

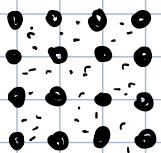
(thermodynamic and transport properties)



EXAMPLE (PROTOTYPE) MANY-BODY HAMILTONIAN

e.g. metallic material

lattice of ions + electrons



$$H_e = \sum_i \frac{\bar{p}_i^2}{2m} + \sum_{i < j} V_{ee}(\bar{r}_i - \bar{r}_j)$$

$$H_i = \sum_I \frac{\bar{P}_I^2}{2M} + \sum_{I < J} V_{ii}(\bar{R}_J - \bar{R}_I)$$

$$H_{ei} = \sum_{i, I} V_{ei}(\bar{R}_I - \bar{r}_i)$$

$$H = H_e + H_i + H_{ei}$$

(certain elements, e.g. lattice structure put in "by hand".)

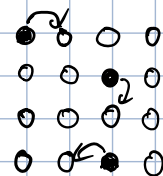
- Not fully realistic (spin, impurities...)
- Valid only down to some length scale (e.g. does not resolve ions' structure)
- Valid only up to some energy scale (too high $T \rightarrow$ lattice melts...)

\rightarrow "Ab initio" approaches (take H as it is...) \rightarrow numerics

\rightarrow Simplify the model to capture most essential elements related to certain phenomenology

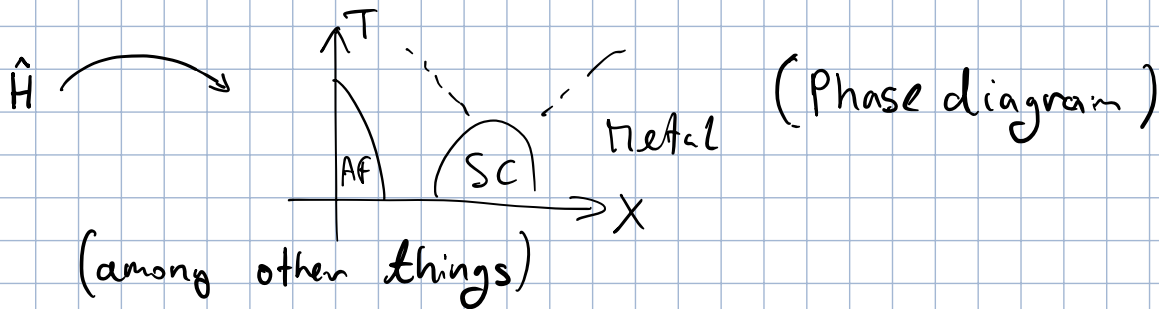
"Reduced" hamiltonian \rightarrow example (2d Hubbard model)

$$\hat{H} = \sum_{i, j, \sigma} t_{ij} c_{j\sigma}^\dagger c_{i\sigma} + U \sum_i \hat{n}_{i\uparrow} \hat{n}_{i\downarrow} \quad (\text{electrons on a lattice})$$



- Almost exclusively approximate approaches (out of exact control)
- Many open questions
- (Supposed-to-be) effective model for Cu-based high- T_c superconductors

What do we mean by "solve the model"?



QM OF MANY-PARTICLE SYSTEMS (NONRELATIVISTIC)

States

System of N identical particles, allowed to move for the time being forget about internal degrees of freedom (like spin).

Use position representation.

For $N=1$ the system state is described by a wavefunction $\psi(\vec{r})$;

$$|\psi(\vec{r})|^2 d^3r \rightarrow \text{probability}$$

Natural generalization: $\psi(\vec{r}) \xrightarrow{N>1} \psi(\vec{r}_1, \vec{r}_2, \dots, \vec{r}_N)$ such that

verified experimentally

$$|\psi(\vec{r}_1, \vec{r}_2, \dots, \vec{r}_N)|^2 \prod_{i=1}^N d^3r_i = \left(\begin{array}{l} \text{probability of finding } N \\ \text{particles in the volume} \\ \prod d^3r_i \text{ around the point} \\ (\vec{r}_1, \dots, \vec{r}_N) \text{ in the } 3N\text{-dimensional} \\ \text{configurational space.} \end{array} \right)$$

However: indistinguishability of particles \Rightarrow constraints on $\psi(\vec{r}_1, \dots, \vec{r}_N)$

e.g. $\psi(\vec{r}_1, \vec{r}_2)$ and $\psi(\vec{r}_2, \vec{r}_1)$ represent the same state.

Indistinguishability \mapsto permuting the arguments of ψ does not change the system state.

$$\psi(\vec{r}_1, \dots, \vec{r}_j, \dots, \vec{r}_k, \dots, \vec{r}_n, \dots, \vec{r}_m, \dots, \vec{r}_N) = \lambda \psi(\vec{r}_1, \dots, \vec{r}_k, \dots, \vec{r}_j, \dots, \vec{r}_n, \dots, \vec{r}_m, \dots, \vec{r}_N) = \lambda^2 \psi(\vec{r}_1, \dots, \vec{r}_j, \dots, \vec{r}_k, \dots, \vec{r}_n, \dots, \vec{r}_m, \dots, \vec{r}_N)$$

$(|\lambda| = 1)$

$$\Rightarrow \lambda^2 = 1, \lambda = \pm 1$$

$\lambda = +1$ - bosons
 $\lambda = -1$ - fermions

Remark: bosons $\rightarrow s \in \mathbb{N}$ (requires relativistic QFT)
 fermions $\rightarrow s \in \mathbb{Z} + \frac{1}{2}$

For fermions: $\vec{r}_j = \vec{r}_k \Rightarrow \psi = 0$ (Pauli exclusion principle)

Basis Forget indistinguishability for a while.

$\{\psi_\nu(\vec{r})\}$ - orthonormal basis for 1-particle states ($\psi_\nu(\vec{r}) = \langle \vec{r} | \nu \rangle$)

We use $\{\psi_\nu(\vec{r})\}$ to construct a basis for N-particle states

Take $\psi(\vec{r}_1 \dots \vec{r}_N)$ (N-particle state)

For a given ν_1 define $A_{\nu_1}(\vec{r}_2 \dots \vec{r}_N) = \int d^3 r_1 \psi_{\nu_1}^*(\vec{r}_1) \psi(\vec{r}_1 \dots \vec{r}_N)$

Knowing the set $\{A_{\nu_1}(\vec{r}_2 \dots \vec{r}_N)\}$ we may recover $\psi(\vec{r}_1 \dots \vec{r}_N)$:

$$\psi(\vec{r}_1, \vec{r}_2 \dots \vec{r}_N) = \sum_{\nu_1} \psi_{\nu_1}(\vec{r}_1) A_{\nu_1}(\vec{r}_2 \dots \vec{r}_N)$$

This is because $\sum_{\nu_1} \psi_{\nu_1}(\vec{r}_1) \int d^3 r_1 \psi_{\nu_1}^*(\vec{r}_1) \psi(\vec{r}_1 \dots \vec{r}_N) = \int d^3 r_1 \underbrace{\sum_{\nu_1} \psi_{\nu_1}^*(\vec{r}_1) \psi_{\nu_1}(\vec{r}_1)}_{=\delta(\vec{r}_1 - \vec{r}_1)} \psi(\vec{r}_1 \dots \vec{r}_N) = \psi(\vec{r}_1, \vec{r}_2 \dots \vec{r}_N)$

Recall the Dirac delta representation:

$$\psi(\vec{r}) = \langle \vec{r} | \psi \rangle = \langle \vec{r} | \sum_{\nu} | \nu \rangle \langle \nu | \psi \rangle = \sum_{\nu} \psi_{\nu}(\vec{r}) \int d^3 r' \psi_{\nu}^*(\vec{r}') \psi(\vec{r}') = \int d^3 r' \underbrace{\left(\sum_{\nu} \psi_{\nu}^*(\vec{r}') \psi_{\nu}(\vec{r}) \right)}_{=\delta(\vec{r} - \vec{r}')} \psi(\vec{r}')$$

$$\Rightarrow \psi(\vec{r}) = \int d^3 r' \left(\sum_{\nu} \psi_{\nu}^*(\vec{r}') \psi_{\nu}(\vec{r}) \right) \psi(\vec{r}') \Rightarrow = \delta(\vec{r} - \vec{r}')$$

Iterate: $A_{\nu_1 \nu_2}(\vec{r}_3 \dots \vec{r}_N) = \int d^3 r_2 \psi_{\nu_2}^*(\vec{r}_2) A_{\nu_1}(\vec{r}_2 \dots \vec{r}_N)$

This is again invertible: $\psi(\vec{r}_1, \vec{r}_2, \vec{r}_3 \dots \vec{r}_N) = \sum_{\nu_1 \nu_2} A_{\nu_1 \nu_2}(\vec{r}_3 \dots \vec{r}_N) \psi_{\nu_1}(\vec{r}_1) \psi_{\nu_2}(\vec{r}_2)$

Repeating N times and, at the end, replacing $\{\vec{r}_i\} \rightarrow \{\vec{r}_i\}$ we obtain:

$$\psi(\vec{r}_1 \dots \vec{r}_N) = \sum_{\nu_1 \dots \nu_N} \underbrace{A_{\nu_1 \dots \nu_N}}_{\text{numerical coefficients}} \psi_{\nu_1}(\vec{r}_1) \psi_{\nu_2}(\vec{r}_2) \dots \psi_{\nu_N}(\vec{r}_N)$$

We expressed the N-body wavefunction as a combination of products of 1-particle wavefunctions.

We did not care about symmetry at this point - see later.

In an arbitrary representation: $\mathcal{H} \mapsto \mathcal{H}_N = \underbrace{\mathcal{H} \otimes \mathcal{H} \otimes \dots \otimes \mathcal{H}}_{N \text{ times}}$