

## 0.1 Pure math

Summary notation: if indices of at least two elements repeat - sum over.  
 Example:  $A_i B_j C_j D_k E_k = \sum_{j,k} A_i B_j C_j D_k E_k$

$$\text{Kronecker delta: } \delta_{ij} = \begin{cases} 1, & \text{if } i = j \\ 0, & \text{if } i \neq j \end{cases}$$

$$\text{Levi-Civita symbol: } \epsilon_{ijk} = \begin{cases} 1, & \text{if } (i, j, k) \subseteq [(1, 2, 3), (2, 3, 1), (3, 1, 2)] \\ -1, & \text{if } (i, j, k) \subseteq [(1, 3, 2), (3, 2, 1), (2, 1, 3)] \\ 0, & \text{if } i = j \vee i = k \vee j = k \end{cases}$$

$$\epsilon_{ijk} = \epsilon_{jki} = \epsilon_{kij} = -\epsilon_{ikj}$$

$$\epsilon_{ijk} \epsilon_{ilm} = \delta_{jl} \delta_{km} - \delta_{jm} \delta_{kl}$$

$$\text{Nabla operator: } \vec{\nabla} = \begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix}$$

Scalar multiplication:  $\vec{A} \cdot \vec{B} = A_i B_i$ ; Vector multiplication:  $\vec{A} \times \vec{B} = \epsilon_{ijk} \vec{e}_i A_j B_k$

Typical coordinates: cartesian  $(x, y, z)$ ; cylindrical  $(\rho, \phi, z)$  where  $x = \rho \cos(\phi), y = \rho \sin(\phi), \rho = \sqrt{x^2 + y^2}, \phi = \arctg(y/x)$ ; spherical  $(r, \theta, \phi)$  where  $x = r \sin(\theta) \cos(\phi), y = r \sin(\theta) \sin(\phi), z = r \cos(\theta), r = \sqrt{x^2 + y^2 + z^2}, \theta = \arccos(z/r), \phi = \arctg(y/x)$ .

$$\text{Lame coefficients: } h_i^2 = \sum_j (\partial_{r'_i} r_j)^2$$

$$\text{Versors: } \partial_i \vec{r} = \vec{e}_i h_i$$

Example: for cylindrical coordinates  $h_\rho^2 = (\partial_\rho x)^2 + (\partial_\rho y)^2 + (\partial_\rho z)^2 = \cos^2(\phi) + \sin^2(\phi) + 0 = 1$

$$\text{Integral implements: } d\vec{l} = h_i dr_i \vec{e}_i, d\vec{A} = h_i h_j dr_i dr_j e_i \vec{\times} e_j, dV = h_i h_j h_k dr_i dr_j dr_k$$

$$\text{Gradient: } \vec{\nabla} f = \frac{\vec{e}_i}{h_i} \partial_i f$$

$$\text{Divergence: } \vec{\nabla} \cdot \vec{A} = \frac{1}{h_1 h_2 h_3} \partial_i (h_j h_k A_i)$$

$$\text{Rotation: } \vec{\nabla} \times \vec{A} = \epsilon_{ijk} \frac{\vec{e}_i}{h_j h_k} \partial_j (h_k A_k)$$

Laplacian:  $\Delta f = \vec{\nabla} \cdot \vec{\nabla} f = \frac{1}{h_1 h_2 h_3} \partial_i \left( \frac{h_j h_k}{h_i} \partial_i f \right)$ , for vector laplacian apply to each element

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0, \vec{\nabla} \times \vec{\nabla} f = 0, \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \triangle \vec{A}$$

„Cuneiform“ formula:  $\nabla \cdot \nabla = \triangle$

Stokes theorem:  $\oint_{\partial A} \vec{B} \cdot d\vec{l} = \iint_A (\vec{\nabla} \times \vec{B}) \cdot d\vec{A}$

Gauss theorem:  $\iint_{\partial V} \vec{B} \cdot d\vec{A} = \iiint_V \vec{\nabla} \cdot \vec{B} dV$

Laplace polynomials:  $P_l(x) = \frac{\partial_x^2 (x^2 - 1)^l}{2^l l!}$

## 0.2 Electrodynamics

Maxwell equations: 
$$\begin{cases} \vec{\nabla} \cdot \vec{D} = \rho \\ \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \times \vec{E} = -\partial_t \vec{B} \\ \vec{\nabla} \times \vec{H} = \vec{j} + \partial_t \vec{D} \end{cases} \quad (\text{differential form})$$

$$\begin{cases} \oint \vec{D} d\vec{A} = \iiint \rho dV \\ \oint \vec{B} d\vec{A} = 0 \\ \oint \vec{E} d\vec{l} = \iint -\partial_t \vec{B} d\vec{A} \\ \oint \vec{H} d\vec{l} = \iint (\vec{j} + \partial_t \vec{D}) d\vec{A} \end{cases} \quad (\text{integral form})$$

Distance notation: 
$$\begin{cases} \vec{r} = \text{distance from zero coordinate to probe} \\ \vec{r}' = \text{distance from zero coordinate to object} \\ \vec{R} = \vec{r} - \vec{r}' = \text{distance from object to probe} \end{cases}$$

### 0.2.1 Electrostatics in vacuum

Coulomb law:  $\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \iiint \rho(\vec{r}') \frac{\vec{R}}{R^3} dV'$

Scalar potential:  $U = \frac{1}{4\pi\epsilon_0} \iiint \frac{\rho(\vec{r}')}{R} dV'$

Electric field energy:  $W_e = \frac{1}{2} \iiint \vec{D} \cdot \vec{E} dV' = \frac{1}{2} \iiint \rho U dV'$

Connection between fields and potentials, force and energy:  $\vec{E} = -\nabla U - \partial_t \vec{A}, \vec{B} = \vec{\nabla} \times \vec{A}, \vec{F} = -\nabla \vec{W}$

Poisson equation:  $\triangle U = \rho$

Multipole approximation:  $U = \frac{1}{4\pi\epsilon_0} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \iiint \rho(\vec{r}') (r')^n P_n(\cos \angle(\vec{r}, \vec{r}')) dV'$

Dipole moment (electric):  $\vec{p} = \iiint \rho(\vec{r}') \vec{r}' dV'$

Electric dipole in field:  $\vec{N} = \vec{p} \times \vec{E}, \vec{F} = (\vec{p} \cdot \vec{\nabla})\vec{E}$

Quadrupole moment:  $Q_{ij} = \iiint \rho(r') (3r'_i r'_j - |r'|^2 \delta_{ij}) dV'$

Dipole field:  $U_{dip} = \frac{1}{4\pi\epsilon_0 r^3} \vec{p} \cdot \vec{r}$

Quadrupole field:  $U_{quad} = \frac{1}{4\pi\epsilon_0 r^5} \vec{r} \cdot \vec{Q} \cdot \vec{r}$

Condensator capacity:  $C = Q/U$

Sphere image (method of images):  $ab = R^2, \frac{q}{a} + \frac{q'}{R} = 0$

### Solutions of Laplace equation - separation of variables

Laplace equation:  $\Delta U = 0$

Cartesian coordinates (2D):  $U = (A_0x + B_0)(C_0y + D_0) + \sum_{n=1}^{\infty} (A_n \sin(k_n x) + B_n \cos(k_n x)) (C_n \sinh(k_n y) + D_n \cosh(k_n y))$

Cylindrical coordinates (2D):  $U = \log \frac{\rho}{A_0} + B_0 + \sum_{n=1}^{\infty} (A_n \rho^n + B_n \rho^{-n}) (C_n \sin n\phi + D_n \cos n\phi)$

Spherical coordinates (special case - rotational symmetry):  $U = \sum_{n=0}^{\infty} (A_n r^n + B_n r^{-(n+1)}) P_n(\cos \theta)$

### 0.2.2 Magnetostatics in vacuum

Biot-Savart law:  $\vec{B} = \frac{\mu_0}{4\pi} \iiint \frac{\vec{I} \times \vec{R}}{R^2}$

Vector potential:  $\vec{A} = \frac{\mu_0}{4\pi} \iiint \frac{\vec{I}(r')}{R} dV'$

Magnetic dipole moment:  $\vec{m} = \iint \vec{j} \times d\vec{A} = \frac{I}{2} \oint \vec{R} \times d\vec{R}, \vec{A}_{dip} = \frac{\mu_0}{4\pi r^2} \vec{m} \times \vec{r}$

Magnetic dipole in field:  $\vec{N} = \vec{m} \times \vec{B}, \vec{F} = \vec{\nabla}(\vec{m} \cdot \vec{B})$

Mutual inductivity:  $L_{12} = \frac{\mu_0}{4\pi} \iint \frac{d\vec{I}_1 \cdot d\vec{I}_2}{R}$

Self-inductivity:  $L = \frac{\iint \vec{B} \cdot d\vec{A}}{I}$

Electromotoric force:  $\varepsilon = -L \partial_t I$

Magnetic field energy:  $W_m = \frac{1}{2} \iiint \vec{B} \cdot \vec{H} dV' = \frac{LI^2}{2}$

### 0.2.3 Electromagnetic materials

Material equations:  $\vec{D} = \epsilon_0 \vec{E} + \vec{P}, \vec{B} = \mu_0(\vec{H} + \vec{M})$

Connection to optical properties:  $\epsilon_0 \mu_0 = \frac{1}{c^2}, \epsilon \mu = n^2$

Ohm's law:  $\vec{j} = \sigma \vec{E}, U = IR$

Bound charges:  $\sigma_b = \vec{P} \cdot \vec{n}, \rho_b = -\vec{\nabla} \cdot \vec{P}$

Bound currents:  $\vec{J}_b = \vec{\nabla} \times \vec{M}, \vec{K}_b = \vec{M} \times \vec{n}$

Boundary conditions - metals:  $V_m = const, E_{||} = 0, B_{\perp} = 0$

Boundary conditions - dielectrics:  $E_{||1} = E_{||2}, D_{\perp 1} - D_{\perp 2} = \sigma_f$

Boundary conditions - magnetics:  $B_{\perp 1} = B_{\perp 2}, H_{||1} - H_{||2} = \vec{K}_f \times \vec{n}$

### 0.2.4 Dynamics

Lorenz force:  $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$

Electric current energy:  $W_c = IU$

Continuity equation:  $\vec{\nabla} \cdot \vec{J} + \partial_t \rho = 0$

Poynting vector:  $\vec{S} = \frac{\vec{E} \times \vec{B}}{\mu_0}$

Maxwell density tensor:  $T_{ij} = \epsilon_0 \left( E_i E_j - \delta_{ij} \frac{E^2}{2} \right) + \frac{1}{mu_0} \left( B_i B_j - \delta_{ij} \frac{B^2}{2} \right)$

Energy flow:  $-\partial_t W = \partial_t \left[ \iiint \epsilon_0 E^2 + \frac{B^2}{\mu_0} dV \right] + \oint \vec{S} \cdot d\vec{A}$

Force in electromagnetic system:  $\vec{F} = \oint \vec{T} d\vec{A} - \frac{1}{c^2} \partial_t \iiint \vec{S} dV$

Connection between Maxwell tensor and Poynting vector:  $\vec{\nabla} \cdot \vec{T} = c^2 \partial_t \vec{S}$

Impedance in transmission line:  $Z_t = \sqrt{\frac{R + i\omega L}{G + i\omega C}}$

Retarded time:  $t_r = t - \frac{|r - r'|}{c}$

$$\text{Relativistic potentials: } U(\vec{r}, t) = \frac{qc}{4\pi\epsilon_0} \frac{1}{|r - r'|c - \vec{r}' \cdot \vec{v}}, \vec{A}(\vec{r}, t) = \frac{U\vec{v}}{c^2}$$